

MIET2510

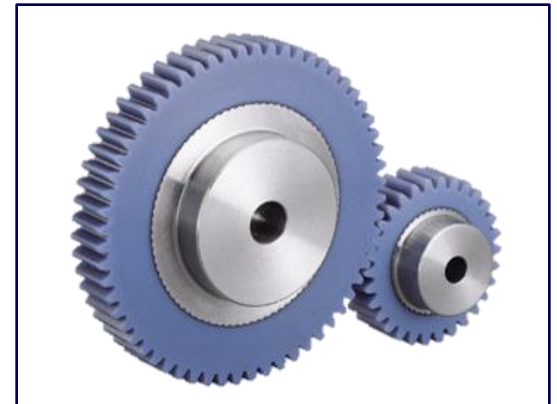
Mechanical Design

Week 6 – Gear Design – Part 1

School of Science and Technology, RMIT Vietnam

Gear Introduction

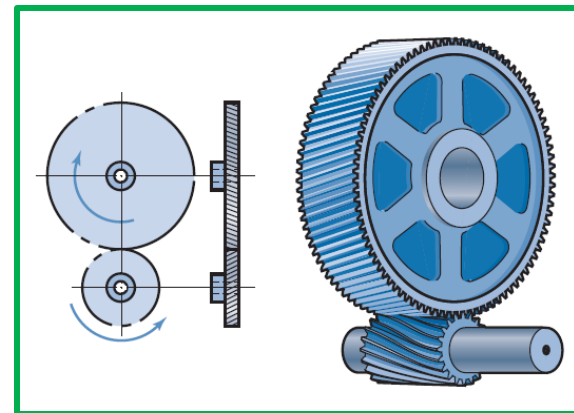
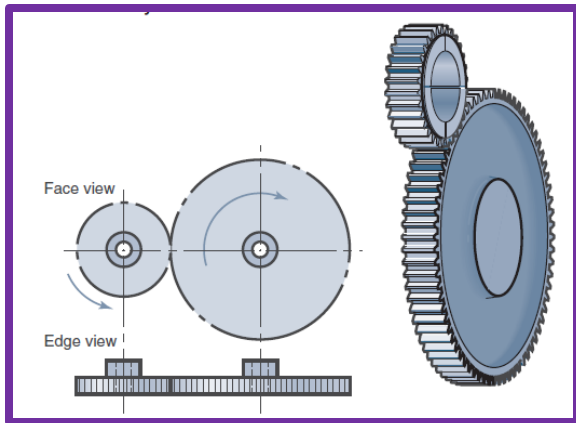
- A **gear** may be thought of as a toothed wheel that, when meshed with another smaller-in-diameter toothed wheel (the pinion), will **transmit rotational motion from one shaft to another**.
- The primary function of a gear is to **transfer power** from one shaft to another while maintaining a fixed ratio between the shaft angular velocities.



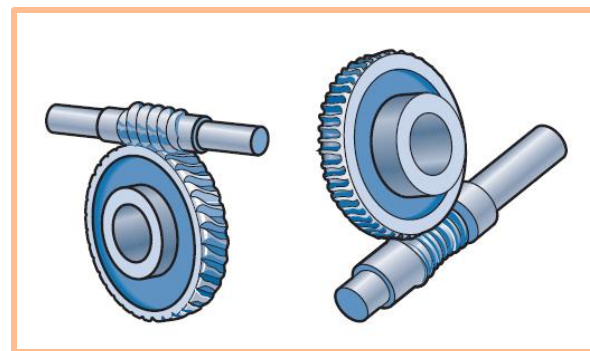
Classification of Gears

Gears can be divided into **three major classes**:

Parallel-axis gears



Nonparallel but coplanar gears



Nonparallel and noncoplanar gears

Gear Materials

Gear materials should have good strength, high stiffness, good wear resistance, good machinability, reasonable cost.

- Hardened steel
- Case hardened steel
- Bronze
- Iron – cast irons
- Non - metallic materials

Gear Materials Selection

The selection of the gear material depends on:

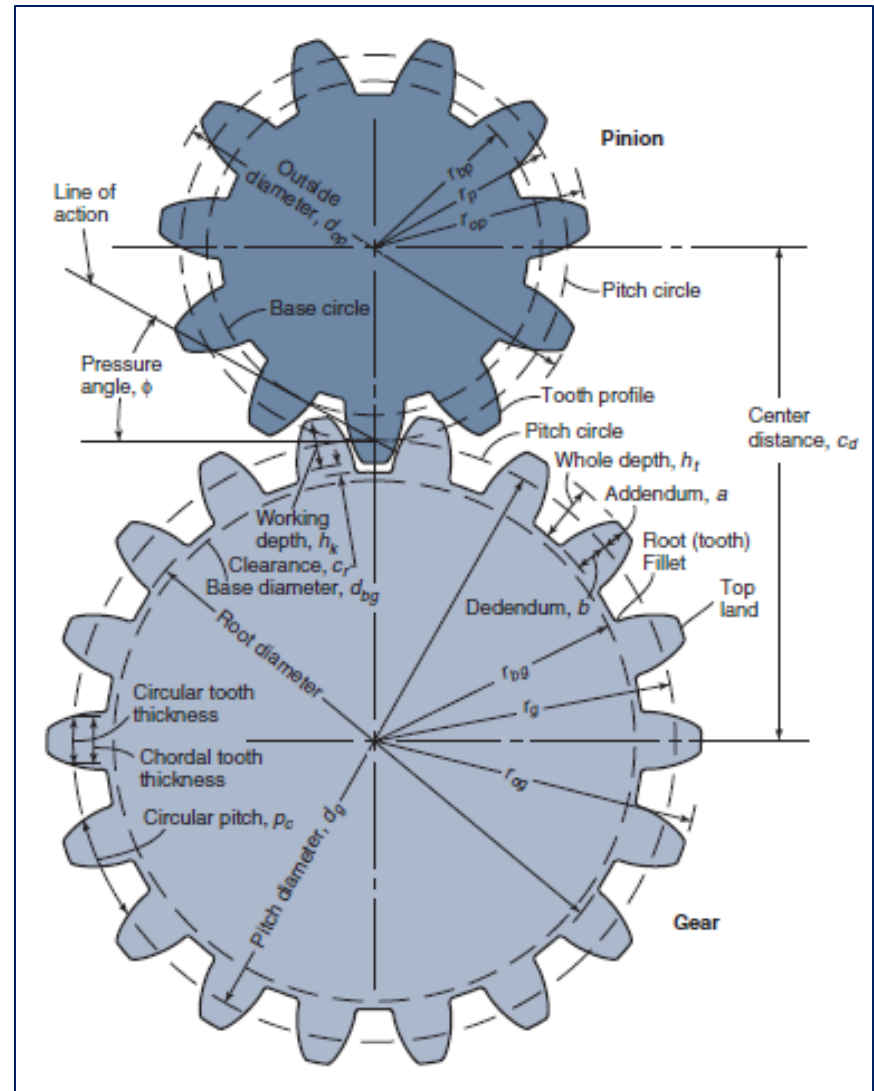
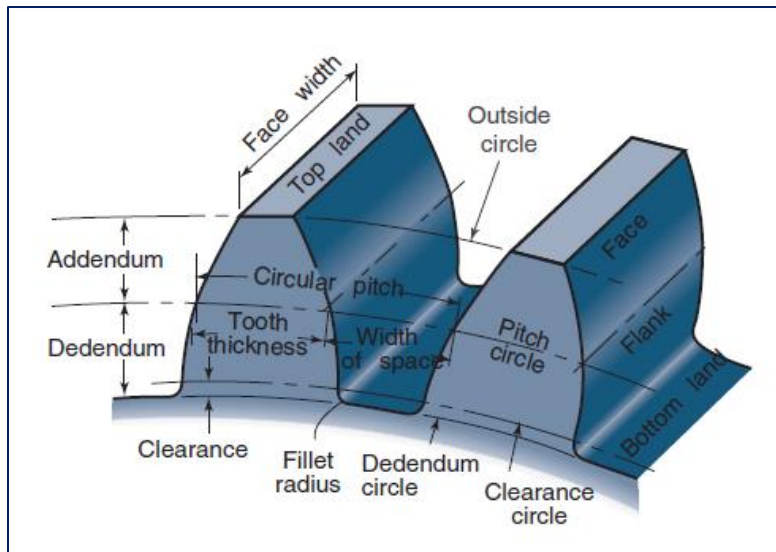
- Peripheral speed
- Degree of accuracy required
- Method of manufacturing
- Required dimensions and weight of the drive
- Allowable stress
- Wear resistance

Spur Gear

A **spur gear** is a cylindrical shaped gear, in which the teeth are parallel to the axis. It is the **most commonly used gear** with a wide range of applications and is the easiest to manufacture.

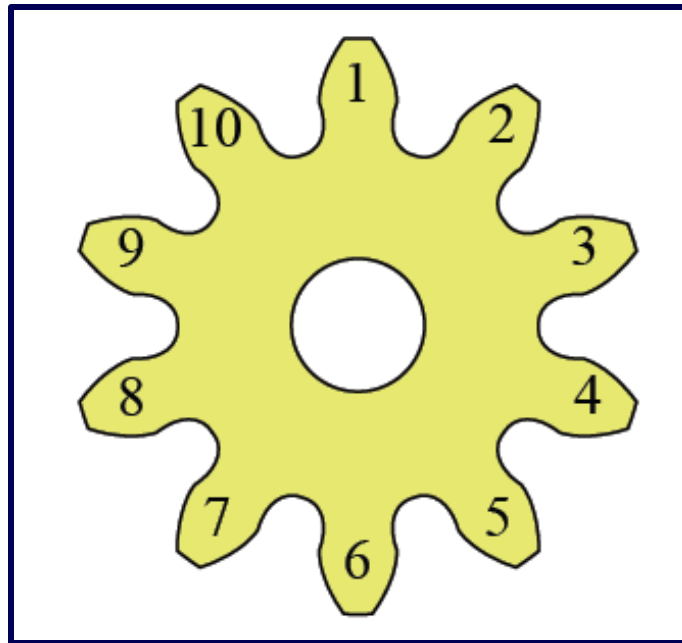


Gear Geometry



Gear Parameter – Fundamental Parameters

- **Number of teeth:** denotes the number of gear teeth.



Gear Parameter – Fundamental Parameters (cont.)

- **Module m:** Module is the ratio of the reference diameter of the gear divided by the number of teeth.

$$m = \frac{D}{N}$$

where D is the pitch circle diameter, mm
 N is the number of the teeth

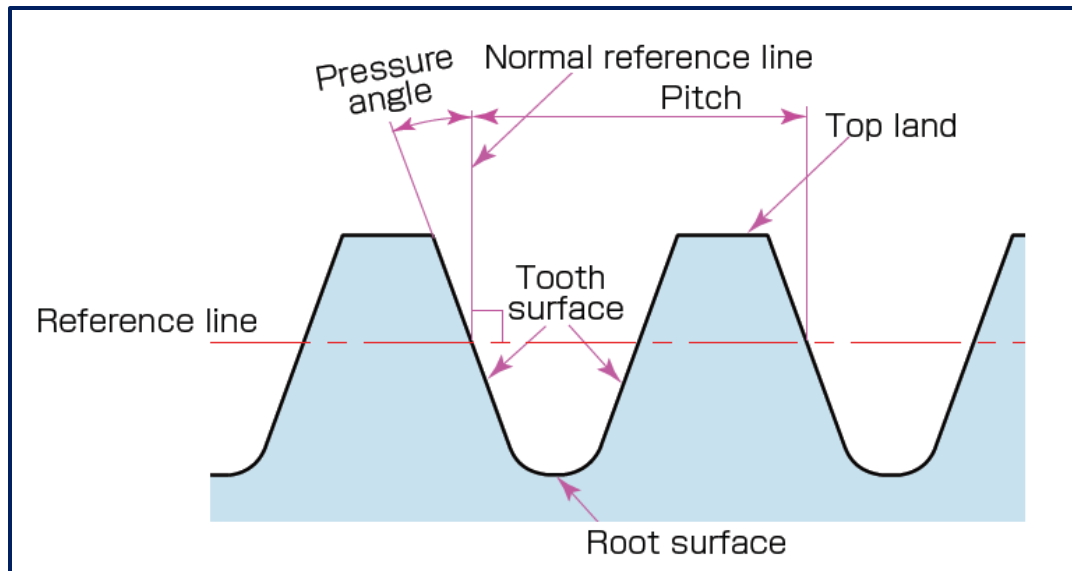
- **Circular pitch:** the distance from any selected reference point on a tooth to a corresponding point on the next tooth measured along the pitch circle

$$p = \frac{\pi D}{N}$$

where D is the pitch circle diameter, mm
 N is the number of the teeth

Gear Parameter – Fundamental Parameters (cont.)

- **Pressure Angle:** is the leaning angle of a gear tooth, an element determining the tooth profile.



Gear Parameter – Related Parameters

➤ Tooth Depth and Thickness

- Tooth depth is determined from the size of module m .

$$h = 2.25 m$$

(= Addendum + Dedendum)

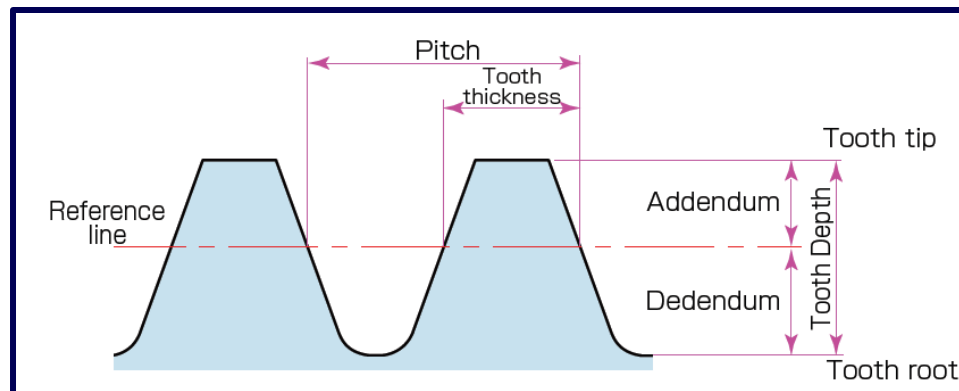
- Addendum is the distance between reference line and tooth tip
- Dedendum is the distance between reference line and tooth root

$$h_a = 1.00 m$$

$$h_f = 1.25 m$$

- Tooth thickness is half of the pitch

$$s = \frac{\pi m}{2}$$



Gear Parameter – Related Parameters (cont.)

➤ Diameter of Gears (Size)

- Reference Diameter

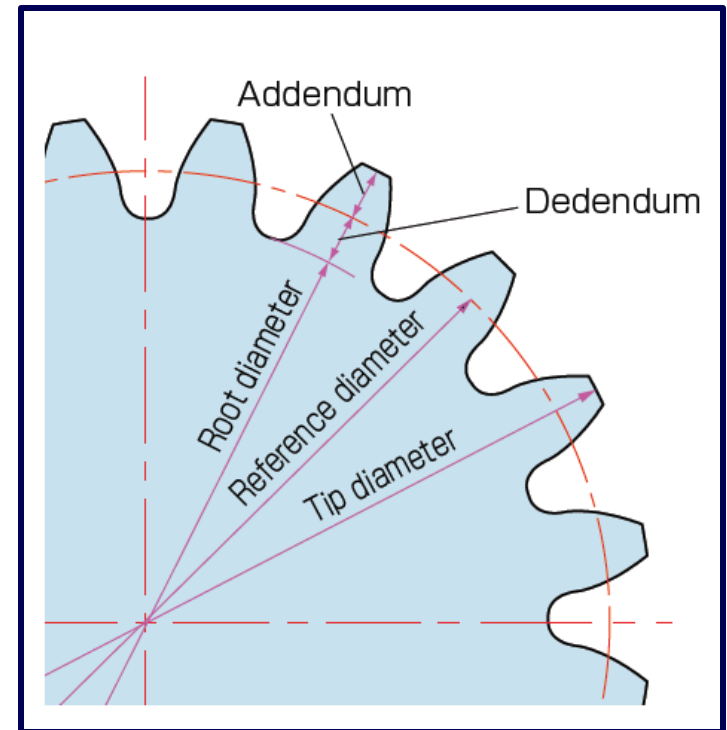
$$d = z m$$

- Tip Diameter

$$d_a = d + 2 m$$

- Root Diameter

$$d_f = d - 2.5 m$$

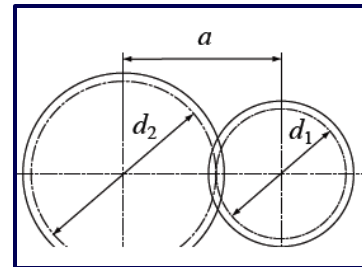


Gear Parameter – Related Parameters (cont.)

➤ Centre distance and Backlash

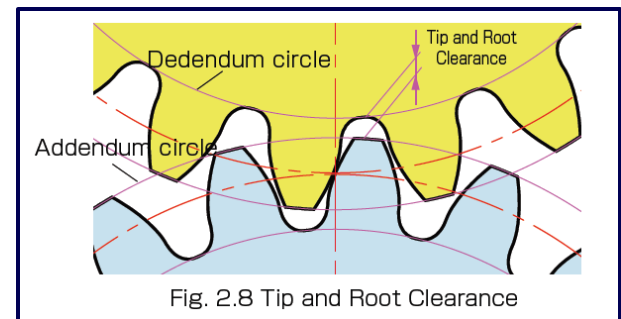
- When a pair of gears are meshed so that their reference circles are in contact, the centre distance (a) is half the sum total of their reference diameters.

$$a = \frac{(d_1 + d_2)}{2}$$



- It is important to consider a proper backlash (play) between tooth surfaces of paired gears, called Tip and Root clearance (c).

$$\begin{aligned} c &= 1.25 m - 1.00 m \\ &= 0.25 m \end{aligned}$$

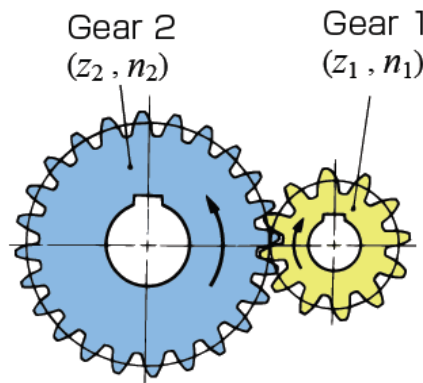


Gear Analysis

➤ Speed Ratio for one – stage gear train:

$$\text{Speed Ratio} = \frac{\text{No. of teeth of driven gear } (z_2)}{\text{No. of teeth of drive gear } (z_1)} = \frac{\text{Rotation of drive gear } (n_1)}{\text{Rotation of driven gear } (n_2)}$$

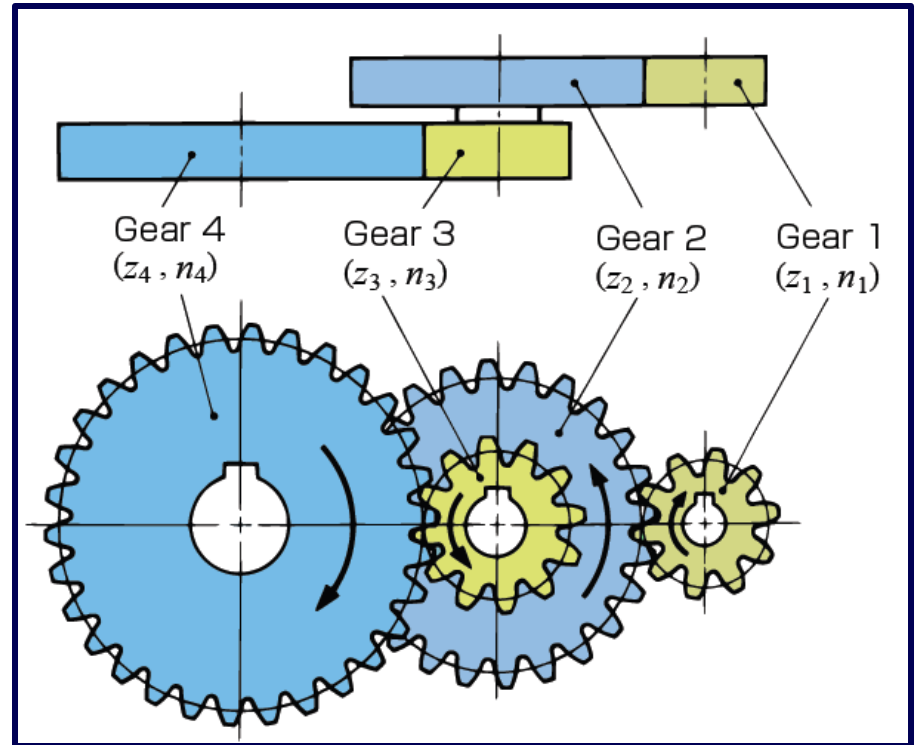
- **Rotational Direction:** The rotational direction of the paired gears is opposite to each other.



Gear Analysis (cont.)

- For two-stage gear train, speed ratio is presented as:

$$i = \frac{z_2}{z_1} \times \frac{z_4}{z_3} = \frac{n_1}{n_2} \times \frac{n_3}{n_4}$$

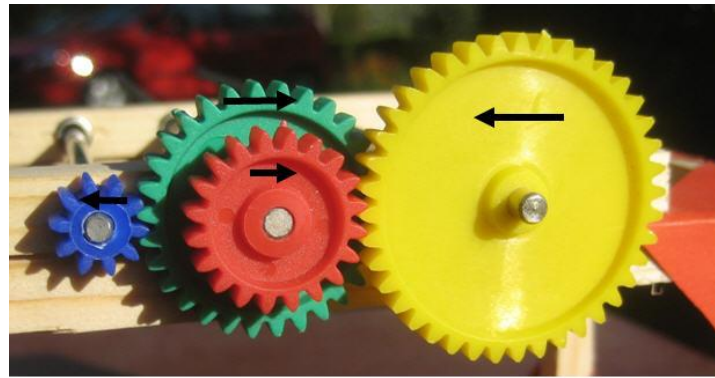
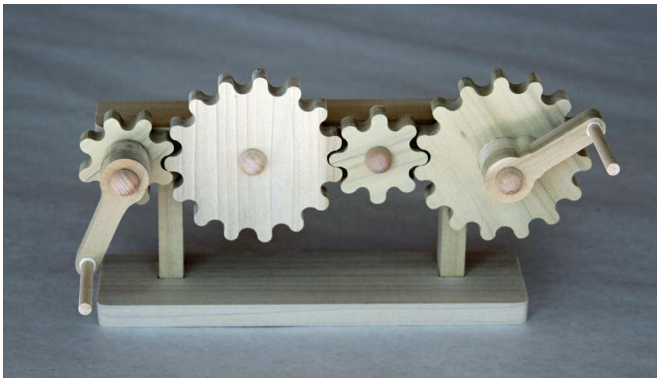


Gear Selection from Catalogue

- Material
- Module
- Number of Teeth
- Pitch Diameter
- Bore Diameter
- Tooth Finish (Standard or High Precision)
- Keyway (No or Yes)
- Allowable Torque

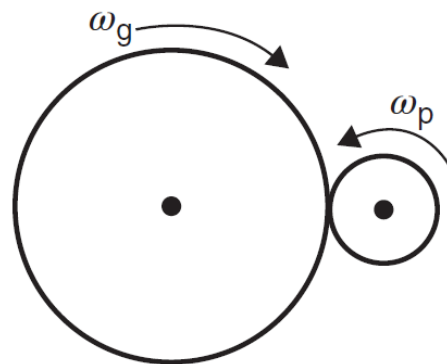
Gear Trains

- **A simple gear train** is one with only one gear per shaft and each shaft rotating about a fixed axis.
- **A compound gear train** is one where two or more gears are fastened together and rotate about a common shaft.

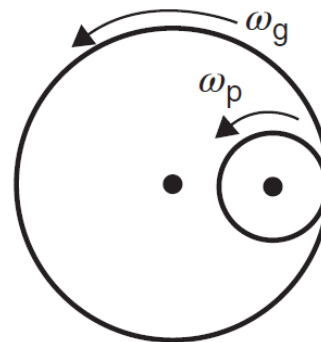


Gear Ratio for meshing gear

- **The gear ratio for externally meshing gear** is considered to be negative since the two gears will rotate in opposite directions.
- **The gear ratio for internally meshing gears** is considered to be positive since both gears will rotate in the same direction



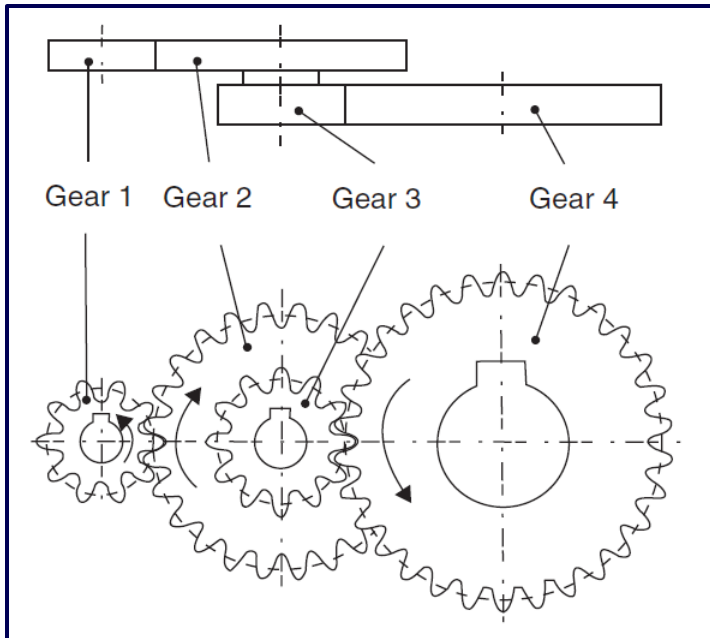
Externally
meshing gears



Internally
meshing gears

Compound Gear Train

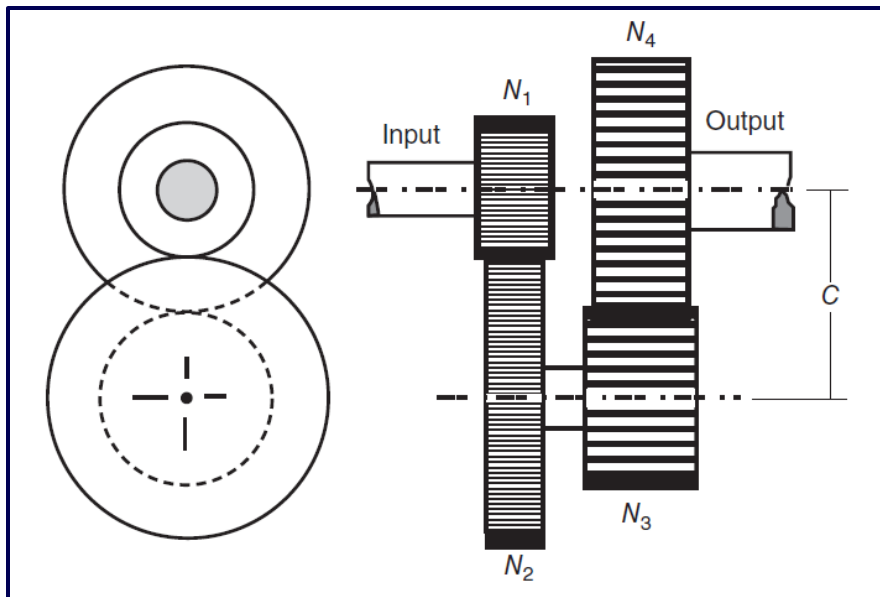
- A **compound gear train** consists of two or more sets of mating gears as shown.



$$\frac{\omega_{\text{out}}}{\omega_{\text{in}}} = \left(-\frac{N_1}{N_2} \right) \left(-\frac{N_3}{N_4} \right) = + \frac{N_1 N_3}{N_2 N_4}$$

Inverted Compound Gear Train

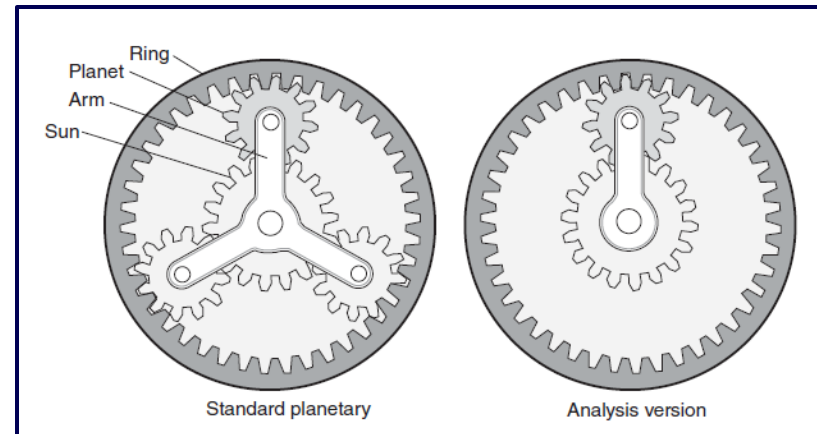
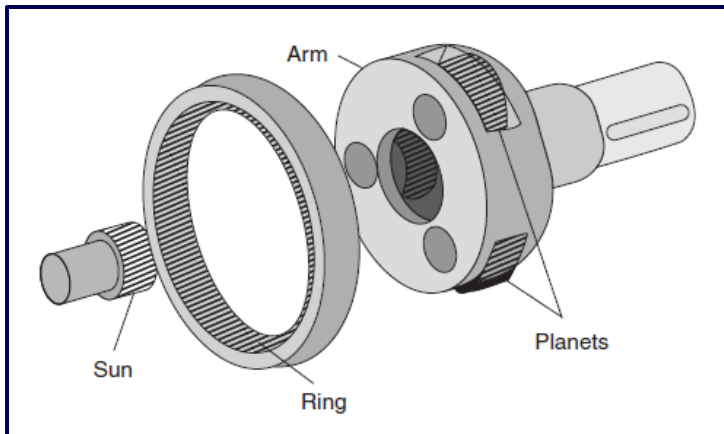
- The **inverted compound gear train** is such that the input shaft and the output shafts are along the same centreline as shown.



$$\frac{\omega_{\text{out}}}{\omega_{\text{in}}} = \left(-\frac{N_1}{N_2} \right) \left(-\frac{N_3}{N_4} \right) = + \frac{N_1 N_3}{N_2 N_4}$$

Planetary Gear Systems

A gear train in which the axis of one or more gears moves relative to the frame is referred to as a planetary or elliptical gear train. The gear at the center is called the **sun** since gears revolve around it. The outer gear is referred to as the **ring** gear. The gears between the ring gear and the sun gear are referred to as **planet gears** since they revolve around the sun gear.





Thank you for your attendance :D

Copyright Claim

The notes contain copyrighted material. It is intended only for students in the class in line with the provisions of Section VB of the Copyright Act for the teaching purposes of the University.

Reference

- *Mechanical Design of Machine Components (2nd) by Ansel C.Ugural.*
- *Mechanical Engineering Design (10th) by Richard G.Budynas and J. Keith Nisbett.*
- *Theory of Machines and Mechanisms (5th) by John J.Uicker, Gordon R.Pennock, Joseph E. Singley.*